

# DiBello Models

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## Parameterized Bayesian Networks

- In a discrete Bayesian Network, the *parameters* are the *conditional probability tables* (CPTs).
- Size of CPT grows exponentially with number of parents.
- In educational models, CPTs should be monotonic: higher skill states should imply higher probability of success.
- When learning CPTs from data, if skill variables are correlated certain combinations will be rare in data:
  - Skill 1 is high and Skill 2 is low
  - Skill 2 is low and Skill 1 is high
  - This makes for low effective sample size (high standard errors) when estimating CPTs from data.

## Conditional Probability Tables

### Lets Make a some Simple CPTs

Load PNetica (which loads Peanut and CPTtools), and start session. Build a blank Network.

```
library(PNetica)

## Loading required package: RNetica
## Loading required package: CPTtools
## Loading required package: lattice
## Loading required package: Peanut
## Loading required package: shiny
## Loading required package: shinyjs
##
## Attaching package: 'shinyjs'
## The following object is masked from 'package:shiny':
##
##   runExample
## The following object is masked from 'package:arm':
##
##   show
## The following object is masked from 'package:lme4':
##
##   show
```

```
## The following object is masked from 'package:Matrix':
##
##      show

## The following objects are masked from 'package:methods':
##
##      removeClass, show

sess <- NeticaSession()
startSession(sess)

## Netica 5.04 Linux (AF), (C) 1992-2012 Norsys Software Corp.
##
## Netica operating without a password; there are some limitations.

tNet <- CreateNetwork("tNet",sess)
```

Let following packages are loaded.

- CPTtools – Tools for building Conditional Probability Tables.
- RNetica – Interface to Netica
- Peanut – Object-oriented parameterized network protocol.
- PNetica – Peanut implementation for Netica

## Create a Simple Network.

Create two parent nodes: Skill1 and Skill2, and a child node, CRItem.

```
Skills <- NewDiscreteNode(tNet,paste("Skill",1:2,sep=""),c("H","M","L"))
CRItem <- NewDiscreteNode(tNet,"CRItem",c("FullCredit","PartialCredit","NoCredit"))
NodeParents(CRItem) <- Skills
NodeParents(Skills[[2]]) <- Skills[1]
```

## The Shape of CPTs

Skill1 has no parents, so unconditional CPT.

```
Skills[[1]] []
```

```
## Skill1.H Skill1.M Skill1.L
##      NA      NA      NA
```

Node that in RNetica the [] operator can be used to access the CPT of a node.

Skill2 has one parent, so conditional CPT.

```
Skills[[2]] []
```

```
## Skill1 Skill2.H Skill2.M Skill2.L
## 1      H      NA      NA      NA
## 2      M      NA      NA      NA
## 3      L      NA      NA      NA
```

CRItem has two parents, for total of nine (3x3) rows.

```
CRItem[]
```

```
## Skill1 Skill2 CRItem.FullCredit CRItem.PartialCredit CRItem.NoCredit
## 1      H      H                  NA                  NA                  NA
```

```
## 2      M      H      NA      NA      NA
## 3      L      H      NA      NA      NA
## 4      H      M      NA      NA      NA
## 5      M      M      NA      NA      NA
## 6      L      M      NA      NA      NA
## 7      H      L      NA      NA      NA
## 8      M      L      NA      NA      NA
## 9      L      L      NA      NA      NA
```

## The [ $\leftarrow$ ] operator for NeticaNodes

RNetica maps the assignment operator for `[]` (`[ $\leftarrow$ ]`) to provide a wide variety of behaviors.

Both `[]` and `[ $\leftarrow$ ]` allow the user to specify a specific row or cell, or group of rows and cells. This is similar, but not quite the same as the `[]` operator behavior for matrixes and data frames.

Single Row:

```
CRItem[Skill1="H",Skill12="H"] <- c(.7,.2,.1)
CRItem["H", "H"]
```

```
## Skill1 Skill2 CRItem.FullCredit CRItem.PartialCredit CRItem.NoCredit
## 1      H      H                0.7                0.2                0.1
```

Multiple Rows:

```
CRItem[Skill2="M"] <- c(.25,.5,.25)
CRItem["M",c("H","M")] <-c(.25,.5,.25)
CRItem[, "M"]
```

```
## Skill1 Skill2 CRItem.FullCredit CRItem.PartialCredit CRItem.NoCredit
## 1      H      M                0.25                0.5                0.25
## 2      M      M                0.25                0.5                0.25
## 3      L      M                0.25                0.5                0.25
```

```
CRItem["M",]
```

```
## Skill1 Skill2 CRItem.FullCredit CRItem.PartialCredit CRItem.NoCredit
## 1      M      H                2.500000e-01        5.000000e-01        2.500000e-01
## 2      M      M                2.500000e-01        5.000000e-01        2.500000e-01
## 3      M      L               -3.396031e+38       -3.396031e+38       -3.396031e+38
```

Fill out a conjunctive model.

```
CRItem["L",] <- c(.1,.2,.7)
CRItem[, "L"] <- c(.1,.2,.7)
CRItem[]
```

```
## Skill1 Skill2 CRItem.FullCredit CRItem.PartialCredit CRItem.NoCredit
## 1      H      H                0.70                0.2                0.10
## 2      M      H                0.25                0.5                0.25
## 3      L      H                0.10                0.2                0.70
## 4      H      M                0.25                0.5                0.25
## 5      M      M                0.25                0.5                0.25
## 6      L      M                0.10                0.2                0.70
## 7      H      L                0.10                0.2                0.70
## 8      M      L                0.10                0.2                0.70
## 9      L      L                0.10                0.2                0.70
```

## Conditional Probability Frames and Conditional Probability Arrays

When there are two or more parent variables, there are two possible views of the CPT:

\* *Conditional Probability Frame* (CPF) which is a data frame where rows represent configurations of parent variables. + First  $p$  rows represent parent configuration + Last  $|States|$  rows represent child states. + Numeric part is the conditional probability table - Note: `calcXXXFrame()` and `calcXXXTable()` methods in CPTtools + CPFs can be used on the RHS of `[<-` operator for `NeticaNodes`, to set the CPT.

\* *Conditional Probability Array* (CPA) which is  $p + 1$  dimensional array.

The functions `as.CPF` and `as.CPA` convert back and forth between the two views:

```
as.CPA(CRItem[])

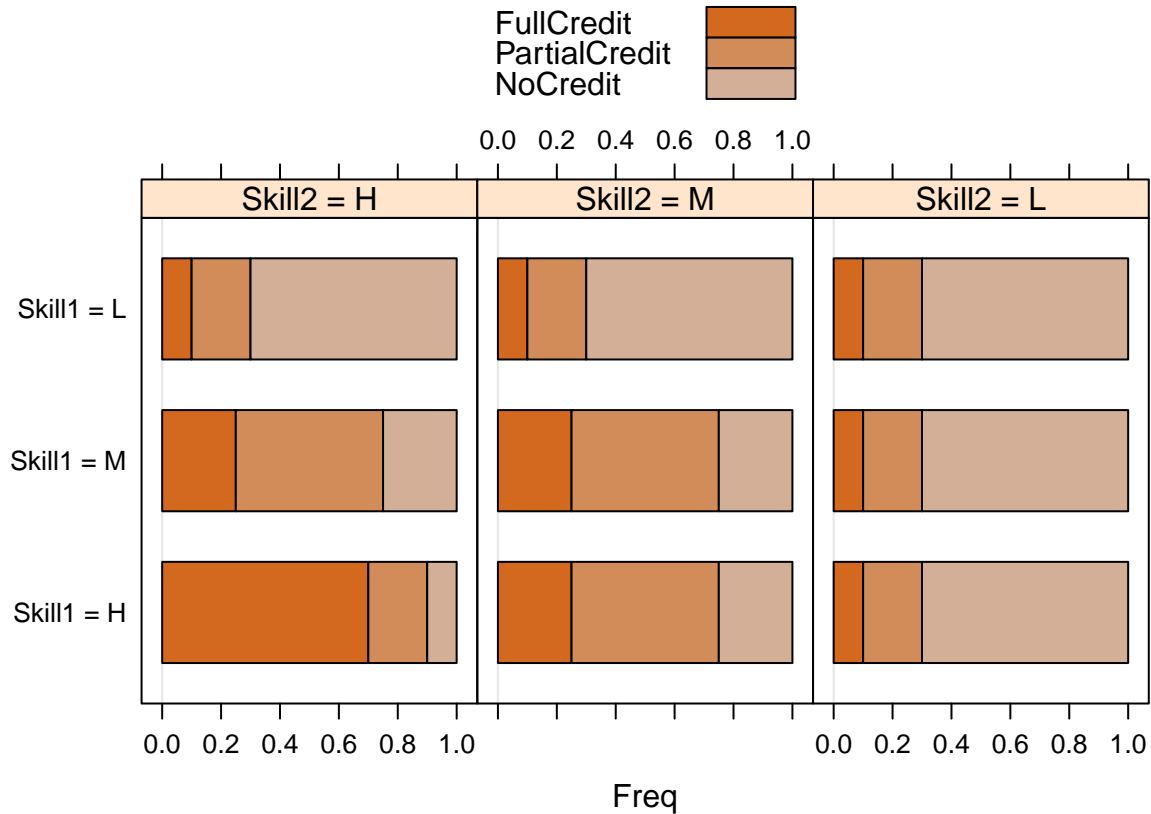
## , , CRItem = FullCredit
##
##      Skill2
## Skill1   H   M   L
##      H 0.70 0.25 0.1
##      M 0.25 0.25 0.1
##      L 0.10 0.10 0.1
##
## , , CRItem = PartialCredit
##
##      Skill2
## Skill1   H   M   L
##      H 0.2 0.5 0.2
##      M 0.5 0.5 0.2
##      L 0.2 0.2 0.2
##
## , , CRItem = NoCredit
##
##      Skill2
## Skill1   H   M   L
##      H 0.10 0.25 0.7
##      M 0.25 0.25 0.7
##      L 0.70 0.70 0.7
##
## attr(,"class")
## [1] "CPA" "array"
```

### Graphing a conditional probability table.

The function `barchart.CPF` (which extends the lattice function `barchart`) will build a visualization of the CPF.

The `baseCol` argument can be any R color specification, it is then used as the base color for the graph.

```
barchart.CPF(CRItem[],baseCol="chocolate")
```



### How far have we come?

- The `CPF` function for `NeticaNodes` is a very convenient way for accessing and manipulating CPTs
- It uses a data-frame representation, the *CPF*
- If we can make a CPF, we can set the table for a node.
- The package `CPTtools` is all about making CPFs!

## The DiBello Models

### A Short History

- When building CPT for Biomass, Lou DiBello had an idea.
- Map each row of the CPT onto an *effective Theta*
- Then use IRT model (Samejima's Graded Response) to calculate CPTs for each row.
- For multivariate parents, use a *structure function* or *combination rule* to combine individual effective thetas for each parent into a single effective theta.
  - *Compensatory*: (weighted) average of parents
  - *Conjunctive*: minimum of parents
  - *Disjunctive*: maximum of parents

## The DiBello procedure

1 Map the states of the parent variables onto the standard normal ( $\theta$ ) scale.

2 Combine the parent variables using a *combination rule* to create a single effective  $\theta$  for each row.

- + The combination rule generally has slope (discrimination) parameters ( $\alpha$ 's or  $a$ 's)
- + The combination rule generally has difficulty (intercept) parameters ( $\beta$ 's or  $b$ 's)
- + Some rules (e.g., `Compensatory`) have multiple- $a$ 's, some (e.g., `OffsetConjunctive`) have multiple- $b$ 's
- + Some link functions allow (or even require) different  $b$ 's for each state of the child variable (step 1)
- + The partial credit link function allows different  $a$ 's as well.

3 Convert the effective  $\theta$ s to conditional probabilities using a *link function* (IRT-like models) + `gradedResponse` – Lou's original suggestion + `partialCredit` – More flexible alternative + `normalLink` – Regression-like model for proficiency variables. - Requires a *link scale parameters*

The function `calcDPCFrame` in the `CPTtools` package does the work. (DPC = Discrete Partial Credit)

## Mapping Parent States onto the Theta Scale

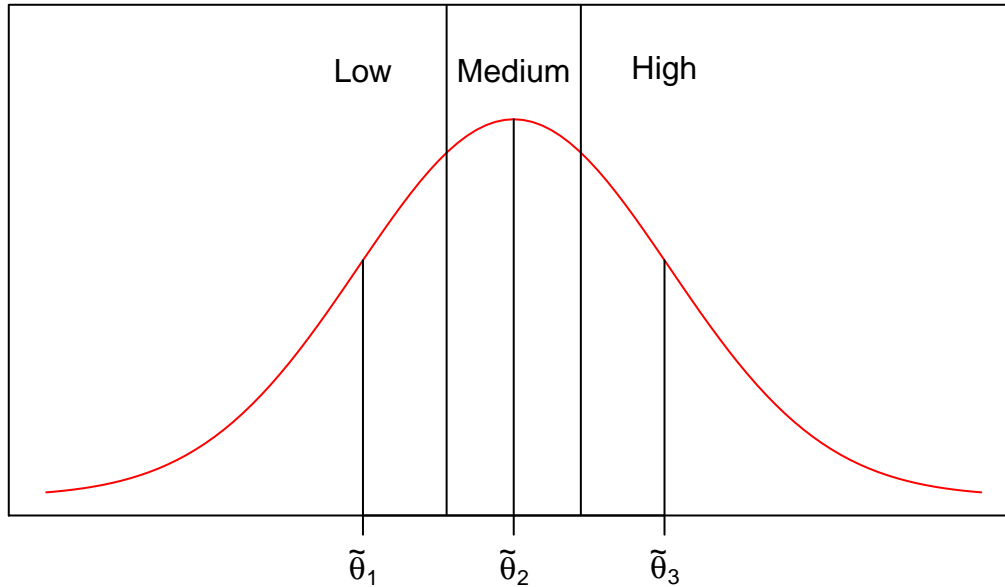
- Effective  $\theta$  scale is a logit scale corresponds to mean 0 SD 1 in a “standard” population.
- Want the effective  $\theta$  values to be equally spaced on this scale
- Want the marginal distribution implied by the effective  $\theta$ s to be uniform (unit of the combination operator)

\*What the effective  $\theta$  transformation to be effectively invertible (this is reason to add the 1.7 to the IRT equation).

## Equally spaced points in Normal Measure

- Assume variable has  $M$  states:  $0, \dots, M - 1$
- Region  $m$  will have lower bound  $m/M$  quantile and upper bound at  $(m + 1)/M$  quantile.
- Midpoint will be at  $(m + \frac{1}{2})/M$  quantile

```
states <- c("Low", "Medium", "High")
M <- length(states)
c <- qnorm((1L:(M-1L))/M, 0, 1)
theta <- qnorm((1L:M -.5)/M, 0, 1)
curve(dnorm(x), xlim=c(-3, 3), xaxt="n", yaxt="n", ylim=c(0, .5), col="red",
      ylab="", xlab="Effective Theta")
segments(c, -.1, c, .6)
segments(theta, -.1, theta, dnorm(theta))
text(theta, .45, states)
axis(1, theta, do.call(expression,
                        lapply(1:M, function (m)
                              substitute(tilde(theta)[m], list(m=m))))))
```



Effective Theta

The function

`effectiveThetas` calculates this.

```
effectiveThetas
```

```
## function (nlevels)
## {
##   rev(qnorm((2 * (1:nlevels) - 1)/(2 * nlevels), 0, 1))
## }
## <environment: namespace:CPTtools>
```

```
effectiveThetas(3)
```

```
## [1] 0.9674216 0.0000000 -0.9674216
```

```
## We will need this for building CPTs later.
```

```
NodeLevels(Skills[[1]]) <- effectiveThetas(PnodeNumStates(Skills[[1]]))
NodeLevels(Skills[[2]]) <- effectiveThetas(PnodeNumStates(Skills[[2]]))
```

## Combination Rules

w\* **Compensatory** – more of one skill compensates for lack of another \* **Conjunctive** – weakest skill dominates relationship \* **Disjunctive** – strongest skill dominates relationship \* **Inhibitor** – minimum threshold of Skill 1 needed, then Skill 2 takes over (special case of conjunctive) Multi-b rules: \* **OffsetConjunctive** – like conjunctive model, but with separate  $b$ 's for each parent instead of separate  $a$ 's \* **Offset Disjunctive** – like disjunctive rule, but with separate  $b$ 's for each parent instead of separate  $a$ 's.

## Compensatory Rule

- Weighted average of inputs
- One  $\alpha$  (slope) for each parent variable ( $k$ ) and state ( $s$ ):  $\alpha_{k,s}$
- One  $\beta$  (difficulty) for each state of the child variable (except the last):  $\beta_s$

$$\tilde{\theta} = \frac{1}{\sqrt{K}} \sum_k \alpha_{k,s} \tilde{\theta}_{k,m_k} - \beta_s$$

\* Factor  $1/\sqrt{K}$  is a variance stabilization term. (Make variance independent of number of parents.)

### Conjunctive and Disjunctive Rules (Multi-a)

- Replace sum (and square root of K) with **min** or **max**
- Conjunctive: All skills needed; weakest skill dominates

$$\tilde{\theta} = \min_k \alpha_{k,s} \tilde{\theta}_{k,m_k} - \beta_s$$

- Disjunctive: Any skills needed; strongest skill dominates

$$\tilde{\theta} = \max_k \alpha_{k,s} \tilde{\theta}_{k,m_k} - \beta_s$$

- Not sure what the different slopes mean in this context

### Conjunctive and Disjunctive Rules (Multi-b)

- Different skills may have different demands in a task
  - Skill 1 must be high, but Skill 2 only medium
- Model this with different difficulties ( $b$ 's) for each parent skill.
- OffsetConjunctive: All skills needed; weakest skill dominates

$$\tilde{\theta} = \alpha_s \min_k (\tilde{\theta}_{k,m_k} - \beta_{k,s})$$

- Disjunctive: Any skills needed; strongest skill dominates

$$\tilde{\theta} = \alpha_s \max_k (\tilde{\theta}_{k,m_k} - \beta_{k,s})$$

### Implementation in CPTtools

- `Compensatory`, `Conjunctive`, `Disjunctive`, `OffsetConjunctive` and `OffsetDisjunctive` are implemented as functions in CPTtools
  - This set is expandable by adding new functions with the same signature
- The function `eThetaFrame` demonstrates how this works.
- Note: Uses  $\log(\alpha)$  rather than  $\alpha$  as slope parameter.

```
eThetaFrame(ParentStates(CRItem), log(c(Skill1=1.2, Skill2=.8)), 0,
             Compensatory)
```

##	Skill1	Skill2	Skill1.theta	Skill2.theta	Effective.theta
## 1	H	H	0.9674216	0.9674216	1.3681407
## 2	M	H	0.0000000	0.9674216	0.5472563
## 3	L	H	-0.9674216	0.9674216	-0.2736281
## 4	H	M	0.9674216	0.0000000	0.8208844
## 5	M	M	0.0000000	0.0000000	0.0000000
## 6	L	M	-0.9674216	0.0000000	-0.8208844
## 7	H	L	0.9674216	-0.9674216	0.2736281
## 8	M	L	0.0000000	-0.9674216	-0.5472563
## 9	L	L	-0.9674216	-0.9674216	-1.3681407



Try changing the slopes and intercepts

## Offset Style Rules:

Almost the same, except now we expect beta to be a vector instead of alpha.

```
eThetaFrame(ParentStates(CRItem),log(1),c(Skill1=.5,Skill2=-.5),
            OffsetConjunctive)
```

##	Skill1	Skill2	Skill1.theta	Skill2.theta	Effective.theta
## 1	H	H	0.9674216	0.9674216	0.4674216
## 2	M	H	0.0000000	0.9674216	-0.5000000
## 3	L	H	-0.9674216	0.9674216	-1.4674216
## 4	H	M	0.9674216	0.0000000	0.4674216
## 5	M	M	0.0000000	0.0000000	-0.5000000
## 6	L	M	-0.9674216	0.0000000	-1.4674216
## 7	H	L	0.9674216	-0.9674216	-0.4674216
## 8	M	L	0.0000000	-0.9674216	-0.5000000
## 9	L	L	-0.9674216	-0.9674216	-1.4674216

Try changing the slopes and intercepts, and changing the rule for `OffsetDisjunctive`

## Link Functions

- Graded Response model
  - Models  $\Pr(X \geq s)$
  - Probabilities are differences between curves
  - To keep the curves from crossing, discrimination parameters must be the same for all  $s$
- Normal (Regression) model
  - Effective theta is mean predictor
  - Add a residual variance (link scale parameter)
  - Calculate probabilities that value falls into certain regions
- Generalized partial credit model
  - Models state transitions:  $\Pr(X \geq s | X \geq s - 1)$
  - Does not need the discrimination parameters to be the same
  - Does not even need the combination rules to be the same

## Graded Response (DiBello–Samejima models)

Samejima's (1969) psychometric model for graded responses

$$\Pr(X_{i,j} \geq k | \theta_i) = \text{logit}^{-1}(1.7(a_j\theta_i - b_{j,k}))$$

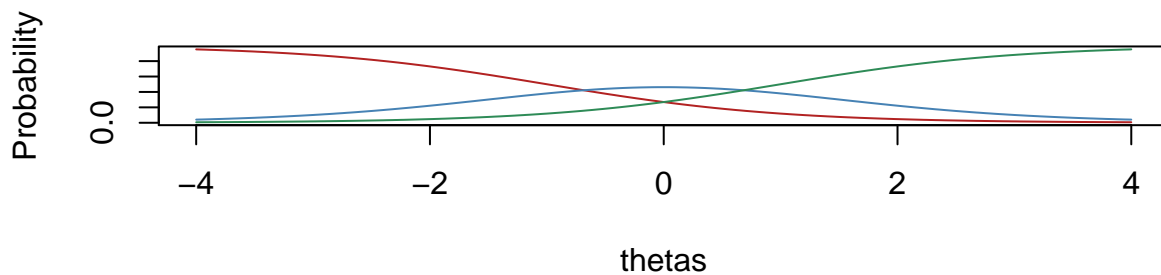
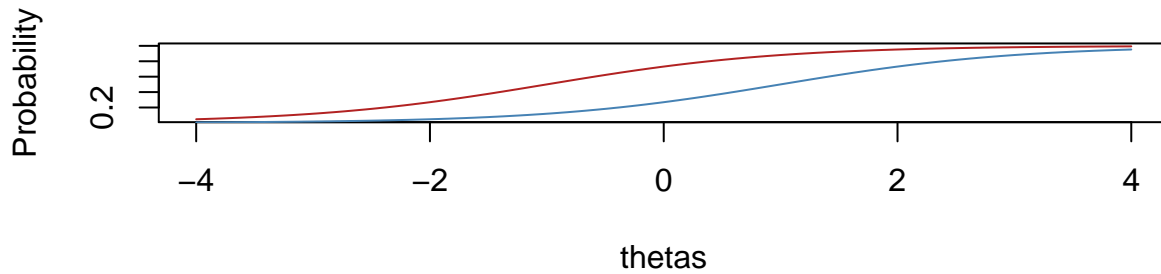
$$\Pr(X_{i,j} = k | \theta_i) = \Pr(X_{i,j} \geq k | \theta_i) - \Pr(X_{i,j} \geq k + 1 | \theta_i)$$

```
a <- 1
b <- c(-1,+1)
thetas <- seq(-4,4,.025)
P1 <- invlogit(a*thetas-b[1])
P2 <- invlogit(a*thetas-b[2])
layout(matrix(1:2),2,1)
```

```

plot(thetas,P1,ylab="Probability",col="firebrick",type="l")
lines(thetas,P2,col="steelblue")
p0 = 1 - P1
p1 = P1 - P2
p2 = P2
plot(thetas,p0,ylab="Probability",col="firebrick",type="l")
lines(thetas,p1,col="steelblue")
lines(thetas,p2,col="seagreen")

```



##

Continuous -> Discrete

Evaluate Samejima's graded response model at the effective theta values.

```

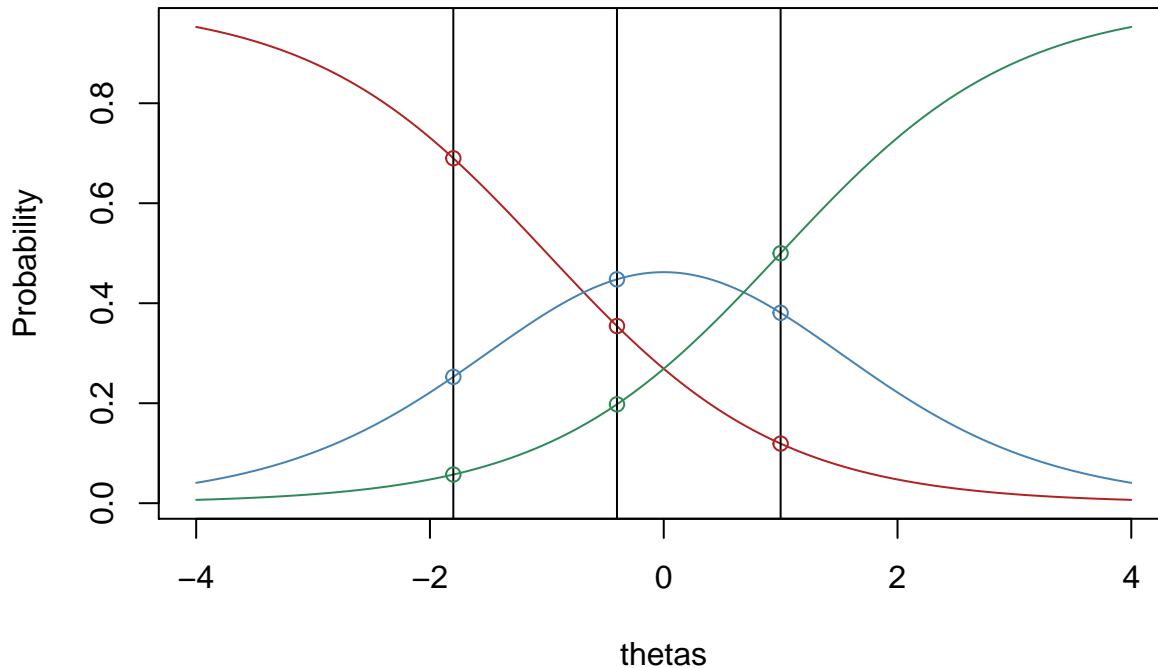
a <- 1
b <- c(-1,+1)
thetas <- seq(-4,4,.025)

P1 <- invlogit(a*thetas-b[1])
P2 <- invlogit(a*thetas-b[2])
p0 = 1 - P1
p1 = P1 - P2
p2 = P2

plot(thetas,p0,ylab="Probability",col="firebrick",type="l")
lines(thetas,p1,col="steelblue")
lines(thetas,p2,col="seagreen")
ethetas <- c(Low=-1.8, Med=-.4, High=1)
P1e <- invlogit(a*ethetas-b[1])
P2e <- invlogit(a*ethetas-b[2])
p0e = 1 - P1e
p1e = P1e - P2e
p2e = P2e
abline(v=ethetas)

```

```
points(ethetas,p0e,col="firebrick")
points(ethetas,p1e,col="steelblue")
points(ethetas,p2e,col="seagreen")
```



```
data.frame(Theta=ethetas,
           State2=round(p2e,3),State1=round(p1e,3),
           State0=round(p0e,3))
```

```
##      Theta State2 State1 State0
## Low   -1.8  0.057  0.253  0.690
## Med   -0.4  0.198  0.448  0.354
## High   1.0  0.500  0.381  0.119
```

## Representing Graded Response Models in Peanut

- Peanut is a framework that allows us to attach the parameters to nodes in the graph.
  - PNetica implements this for NeticaNode objects
- PnodeLink(node) accesses the link function
  - Should have value “gradedResponse” for graded response models.
- PnodeRules(node) accesses the rules.
  - For now, stick to multiple-a types: Compensatory, Conjunctive and Disjunctive.
- PnodeLnAlphas(node) or PnodeAlphas(node) gives the slope parameters.
  - This should be a vector which components corresponding to the parents.
    - In general, vectors are used to represent multiple parents.
- PnodeBetas(node) gives the difficulty parameters.
  - This should be a list with one fewer elements than there are states (the last state is used for normalization).
  - In general, lists are used to represent multiple states.
- BuildTable(node) builds the table.
  - NodeLevels of parents need to be set.
  - NodePriorWeight (used in learning algorithm) needs to be set.

```

CRItem <- Pnode(CRItem) ## Force into Pnode protocol.
PnodeLink(CRItem) <- "gradedResponse"
PnodeRules(CRItem) <- "Compensatory"
PnodeAlphas(CRItem) <- c(1.2, .8)
PnodeBetas(CRItem) <- list(.25, -.25)
PnodePriorWeight(CRItem) <- 10 ## Used for learning
calcDPCFrame(ParentStates(CRItem), PnodeStates(CRItem),
             PnodeLnAlphas(CRItem), PnodeBetas(CRItem),
             PnodeRules(CRItem), PnodeLink(CRItem))

```

```

## Skill1 Skill2 FullCredit PartialCredit NoCredit
## 1      H      H 0.86998648 0.06997425 0.06003927
## 2      M      H 0.62371241 0.17128816 0.20499942
## 3      L      H 0.29107519 0.19888420 0.51004061
## 4      H      M 0.72521985 0.13540669 0.13937347
## 5      M      M 0.39532092 0.20935817 0.39532092
## 6      L      M 0.13937347 0.13540669 0.72521985
## 7      H      L 0.51004061 0.19888420 0.29107519
## 8      M      L 0.20499942 0.17128816 0.62371241
## 9      L      L 0.06003927 0.06997425 0.86998648

```

```

BuildTable(CRItem)
CRItem <- CompensatoryGadget(CRItem)

```

```

##
## Listening on http://127.0.0.1:4454

```

```
CRItem[]
```

```

## Skill1 Skill2 CRItem.FullCredit CRItem.PartialCredit CRItem.NoCredit
## 1      H      H 0.86998647 0.06997425 0.06003927
## 2      M      H 0.62371242 0.17128816 0.20499942
## 3      L      H 0.29107520 0.19888420 0.51004058
## 4      H      M 0.72521985 0.13540669 0.13937347
## 5      M      M 0.39532092 0.20935817 0.39532092
## 6      L      M 0.13937347 0.13540669 0.72521985
## 7      H      L 0.51004058 0.19888420 0.29107520
## 8      M      L 0.20499942 0.17128816 0.62371242
## 9      L      L 0.06003927 0.06997425 0.86998647

```

## Don't Cross the curves!

**Egon Spengler:** There's something very important I forgot to tell you.

**Peter Venkman:** What?

**Egon:** Don't cross the streams.

**Venkman:** Why?

**Egon:** It would be bad.

**Venkman:** I'm fuzzy on the whole good/bad thing. What do you mean, "bad"?

**Egon:** Try to imagine all life as you know it stopping instantaneously, and every molecule in your body exploding at the speed of light.

**Ray Stantz:** [shocked gasp] Total protonic reversal.

**Venkman:** Right. That's bad. Okay. All right. Important safety tip. Thanks, Egon.

*Ghostbusters*

Actually, not as bad as crossing the proton beams, can produce negative probabilities.

CPTtools corrects, but still puts restrictions on parameters.

In particular, must have a common discrimination for all states of the child variable to ensure curves don't cross.

## Downslide of Graded Response Model

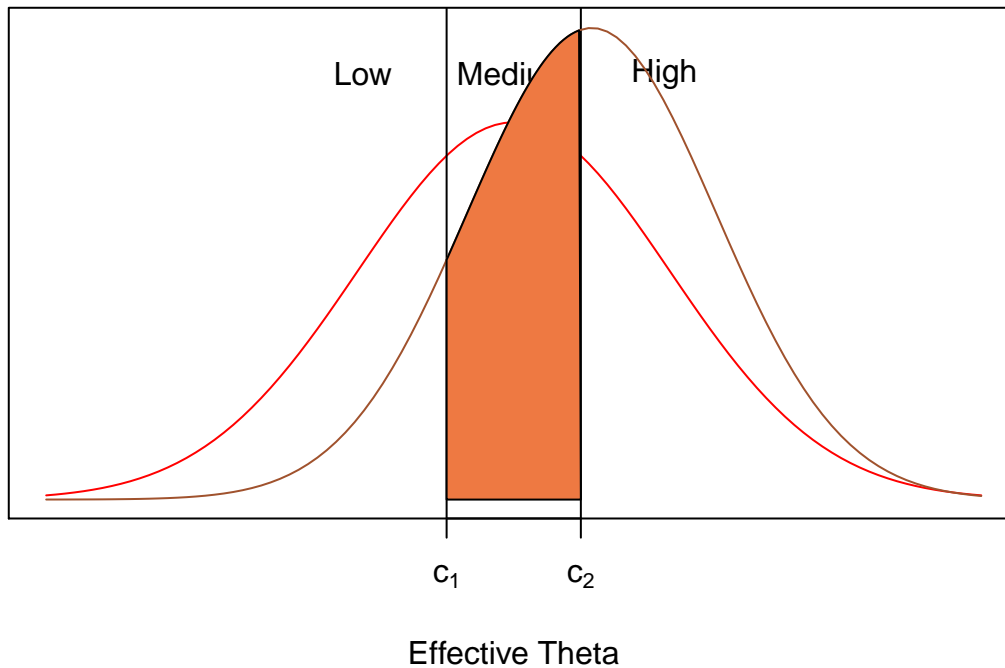
- Need to keep curves from crossing restricts discrimination parameter
  - In *Physics Playground (v. 1)* for some levels difference between **Silver** trophy and **Gold** trophy had more evidence (higher discrimination) than difference between **Silver** and **none**
  - All steps must have the same parent variables and the same combination rule.
- Models probability of achieving certain level of performance, not step between levels.
- Generalized Partial Credit (GPC) model does not have these downsides.
- Note Graded Response and GPC are the same when child variable has only two states.

## Normal (Regression) Model

- As with effective theta transformation, start by dividing theta region up into equally spaced intervals
- Calculate offset curve:
  - mean is effective theta
  - SD,  $s$ , is *link scale parameter* \*Conditional probabilities:
  - area under curve between cut points

```
states <- c("Low", "Medium", "High")
M <- length(states)
c <- qnorm((1L:(M-1L))/M, 0, 1)
thetas <- qnorm((1L:M -.5)/M, 0, 1)
curve(dnorm(x), xlim=c(-3, 3), xaxt="n", yaxt="n", ylim=c(0, .5), col="red",
      ylab="", xlab="Effective Theta")
segments(c, -.1, c, .6)
text(thetas, .45, states)
axis(1, c, do.call(expression,
                    lapply(1:(M-1), function (m)
                          substitute(c[m], list(m=m))))))

theta <- .5
sig <- .8
curve(dnorm(x, theta, sig), col="sienna", add=TRUE)
cc <- seq(c[1], c[2], .025)
polygon(c(c[1], cc, c[2]), c(0, dnorm(cc, theta, sig), 0), angle=45, col="sienna2")
```



```
cplus <- c(-Inf,c,Inf)
pvals <- diff(pnorm(cplus,theta,sig))
names(pvals) <- states
pvals
```

```
##      Low   Medium   High
## 0.1223318 0.3431666 0.5345016
```

### Normal Link (Regression Model) features

- Link function is inverse of the mapping from states to effective thetas
  - Rounding error, but no scale distortion
  - Good for proficiency variables
- Can be used for no parent case.
- Often better to use intercept (negative difficulty) rather than difficulty.
- Can use  $R^2$  instead of the link scale parameter,  $\sigma$

$$R^2 = \frac{1/K \sum_k \alpha_{k,s}^2}{1/K \sum_k \alpha_{k,s}^2 + \sigma^2}$$

- Note: Latent (tetrachoric) correlations, not observed score correlations
- Can use factor analysis output to get model structure and parameters (Almond, 2010)

### Normal Link: No Parent case

- `PnodeLink(node)` is now “normalLink”
- Now need `PnodeLinkScale(node)`, residual standard deviation ( $\sigma$ )
- Rule doesn’t matter, use `PnodeRules(node)="Compensatory"`
- Should be only one `PnodeBeta(node)`

```

Skill11 <- Pnode(Skills[[1]]) ## Force into Pnode protocol.
PnodeLink(Skill11) <- "normalLink"
PnodeLinkScale(Skill11) <- .8
PnodeRules(Skill11) <- "Compensatory"
PnodeAlphas(Skill11) <- numeric()
PnodeBetas(Skill11) <- list(.25)
PnodePriorWeight(Skill11) <- 10 ## Used for learning
calcDPCFrame(ParentStates(Skill11),PnodeStates(Skill11),
             PnodeLnAlphas(Skill11),PnodeBetas(Skill11),
             PnodeRules(Skill11),PnodeLink(Skill11),
             PnodeLinkScale(Skill11))

```

```

##           H           M           L
## 1 0.1974099 0.391954 0.4106361

```

```

BuildTable(Skill11)
Skill11 <- RegressionGadget(Skill11)

```

```

##
## Listening on http://127.0.0.1:4454

```

```
Skill11[]
```

```

## Skill11.H Skill11.M Skill11.L
## 0.1974099 0.3919540 0.4106360

```

## Normal Link: One Parent case

- PnodeLink(node) is now “normalLink”
- Now need PnodeLinkScale(node), residual standard deviation ( $\sigma$ )
- Works best with PnodeRules(node)="Compensatory"
- Should be only one PnodeBeta(node)

```

Skill12 <- Pnode(Skills[[2]]) ## Force into Pnode protocol.
PnodeLink(Skill12) <- "normalLink"
PnodeLinkScale(Skill12) <- .6
PnodeRules(Skill12) <- "Compensatory"
PnodeAlphas(Skill12) <- c(.8)
PnodeBetas(Skill12) <- list(-.25)
PnodePriorWeight(Skill12) <- 10 ## Used for learning
calcDPCFrame(ParentStates(Skill12),PnodeStates(Skill12),
             PnodeLnAlphas(Skill12),PnodeBetas(Skill12),
             PnodeRules(Skill12),PnodeLink(Skill12),
             PnodeLinkScale(Skill12))

```

```

## Skill11           H           M           L
## 1      H 0.83859093 0.1537431 0.007665989
## 2      M 0.38162636 0.4900907 0.128282900
## 3      L 0.05579268 0.3824800 0.561727270

```

```

BuildTable(Skill12)
Skill12 <- RegressionGadget(Skill12)

```

```

##
## Listening on http://127.0.0.1:4454

```

```
Skill12[]
```

```
## Skill1 Skill2.H Skill2.M Skill2.L
## 1      H 0.83859092 0.1537431 0.007665989
## 2      M 0.38162637 0.4900908 0.128282905
## 3      L 0.05579268 0.3824801 0.561727285
```

## Partial Credit Models

- Observable variable takes on states  $0, \dots, S$
- Model transition probabilities:

$$P_{s|s-1}(\tilde{\theta}) = \Pr(X \geq s | X \geq s-1, \tilde{\theta}) = \text{logit}^{-1}(1.7Z_s(\tilde{\theta}))$$

- Define  $Z_0() = 0$ .
- $Z_s()$  can vary with  $s$ :
  - Different parameters
  - Different functional forms
  - Can easily switch between multi-a and multi-b combination rules
  - Can use only a subset of the parents!
- Need to define combination rule and parameters for each state (except state 0).
- `PnodeLnAlphas`, `PnodeBetas` and `PnodeRules` are now lists (one element per state)

## Partial Credit Link:

- Probability of  $X$  being in state  $s$  is:

$$\Pr(X = s | \tilde{\theta}) = \frac{\prod_{r=0}^s P_{r|r-1}(\tilde{\theta})}{C},$$

where  $C$  is a normalization constant.

- Can convert the products to sums

$$\Pr(X = s | \tilde{\theta}) = \frac{\exp(1.7 \sum_{r=0}^s Z_r(\tilde{\theta}))}{\sum_{R=0}^S \exp(1.7 \sum_{r=0}^R Z_r(\tilde{\theta}))}$$

## Simple Case 1: Multiple-A rules

- These look a lot like graded response
- `PnodeLink(pnode) = "partialCredit"`
- `PnodeRules(pnode)` is a single value
  - “Compensatory”, “Conjunctive”, “Disjunctive”
- `PnodeLnAlphas(pnode)` is a *vector* corresponding to parents
- `PnodeBetas(pnode)` is a *list* corresponding to states.
  - $Z_s()$  has the same functional form and the same parameters except for  $b$ 's
- Use `CompensatoryGadget` to edit this style table.

```
CRItem <- Pnode(CRItem) ## Force into Pnode protocol.
PnodeLink(CRItem) <- "partialCredit"
PnodeRules(CRItem) <- "Compensatory"
PnodeAlphas(CRItem) <- c(1.2, .8)
PnodeBetas(CRItem) <- list(.25, -.25)
```



```

PnodePriorWeight(CRItem) <- 10 ## Used for learning
calcDPCFrame(ParentStates(CRItem),PnodeStates(CRItem),
             PnodeLnAlphas(CRItem),PnodeBetas(CRItem),
             PnodeRules(CRItem),PnodeLink(CRItem))

## Skill1 Skill2 FullCredit PartialCredit NoCredit
## 1      H      H 0.862821165      0.1289427 0.008236118
## 2      M      H 0.568546469      0.3430058 0.088447725
## 3      L      H 0.167478982      0.4079015 0.424619527
## 4      H      M 0.694323128      0.2630736 0.042603245
## 5      M      M 0.283318992      0.4333620 0.283318992
## 6      L      M 0.042603245      0.2630736 0.694323128
## 7      H      L 0.424619527      0.4079015 0.167478982
## 8      M      L 0.088447725      0.3430058 0.568546469
## 9      L      L 0.008236118      0.1289427 0.862821165

```

```

BuildTable(CRItem)
CRItem <- CompensatoryGadget(CRItem)

```

```

##
## Listening on http://127.0.0.1:4454

```

```
CRItem[]
```

```

## Skill1 Skill2 CRItem.FullCredit CRItem.PartialCredit CRItem.NoCredit
## 1      H      H      0.862821162      0.1289427      0.008236118
## 2      M      H      0.568546474      0.3430058      0.088447727
## 3      L      H      0.167478979      0.4079015      0.424619526
## 4      H      M      0.694323123      0.2630736      0.042603247
## 5      M      M      0.283318996      0.4333620      0.283318996
## 6      L      M      0.042603247      0.2630736      0.694323123
## 7      H      L      0.424619526      0.4079015      0.167478979
## 8      M      L      0.088447727      0.3430058      0.568546474
## 9      L      L      0.008236118      0.1289427      0.862821162

```

## Simple Case 2: Multiple-B rules

- These look a lot like multiple-a rules.
- PnodeLink(pnode) = "partialCredit"
- PnodeRules(pnode) is a single value
  - “OffsetConjunctive”, “OffsetDisjunctive”
- PnodeLnAlphas(pnode) is a *list* corresponding to states
- PnodeBetas(pnode) is a *vector* corresponding to parent.
  - $Z_s()$  has the same functional form and the same parameters except for  $b$ 's
- Use OffsetGadget to edit this style table.

```

CRItem <- Pnode(CRItem) ## Force into Pnode protocol.
PnodeLink(CRItem) <- "partialCredit"
PnodeRules(CRItem) <- "OffsetDisjunctive"
PnodeAlphas(CRItem) <- list(1.2,.8)
PnodeBetas(CRItem) <- c(.25, -.25)
PnodePriorWeight(CRItem) <- 10 ## Used for learning
calcDPCFrame(ParentStates(CRItem),PnodeStates(CRItem),
             PnodeLnAlphas(CRItem),PnodeBetas(CRItem),
             PnodeRules(CRItem),PnodeLink(CRItem))

```

```
## Skill1 Skill2 FullCredit PartialCredit NoCredit
## 1 H H 0.90960164 0.0759038 0.01449456
## 2 M H 0.90960164 0.0759038 0.01449456
## 3 L H 0.90960164 0.0759038 0.01449456
## 4 H M 0.75835519 0.1754952 0.06614958
## 5 M M 0.49311841 0.2961154 0.21076617
## 6 L M 0.49311841 0.2961154 0.21076617
## 7 H L 0.75835519 0.1754952 0.06614958
## 8 M L 0.19980267 0.3327296 0.46746769
## 9 L L 0.05957531 0.2574386 0.68298611
```

```
BuildTable(CRItem)
CRItem <- OffsetGadget(CRItem)
```

```
##
## Listening on http://127.0.0.1:4454
```

```
CRItem[]
```

```
## Skill1 Skill2 CRItem.FullCredit CRItem.PartialCredit CRItem.NoCredit
## 1 H H 0.90960163 0.0759038 0.01449456
## 2 M H 0.90960163 0.0759038 0.01449456
## 3 L H 0.90960163 0.0759038 0.01449456
## 4 H M 0.75835520 0.1754952 0.06614958
## 5 M M 0.49311841 0.2961154 0.21076617
## 6 L M 0.49311841 0.2961154 0.21076617
## 7 H L 0.75835520 0.1754952 0.06614958
## 8 M L 0.19980267 0.3327296 0.46746770
## 9 L L 0.05957531 0.2574386 0.68298608
```

## Discrete Partial Credit model unleashed

- `PnodeRules(pnode)` is now a *list*
  - different rule for each state
- `PnodeLnAlphas(node)` is also a *list*
  - elements correspond to states
  - will be a vector or scalar according to corresponding rule.
- `PnodeBetas(node)` is also a *list*
  - elements correspond to states
  - will be a vector or scalar according to corresponding rule.
- A *list* corresponds to states of child variable (except last)
  - If a vector or scalar shows up where a list is expected, the same value is used for all states.
- A *vector* (within a list) corresponds to parents
- Could eliminate some parents (0 alpha, or infinite beta)
  - Or use *inner* (node specific) *Q*-matrix

## Example: Math Word Problem

- Based on unpublished analysis by Cocke and Guo (personal communication 2011-07-11)

- Next Generation Sunshine State Standards Benchmark, MA.6.A.5.1, “Use equivalent forms of fractions, decimals, and percents to solve problems” (NGSSS, 2013)
- Sample problem: > John scored 75% on a test and Mary has 8 out of 12 correct on the same test. Each test item is worth the same amount of points. Who has the better score?

## Scoring Rubric

State	Description	Skills
No Credit or off track	Null response	N/A
Partial Credit 1	Recognizes 75% and 8/12 as key elements	Mathematical Language
Partial Credit 2	Converts two fractions to a common form	Convert Fractions
Full Credit	Makes the correct comparison	Compare Fractions & Math Lang.

## Model Refinement

- Collapse “Partial Credit 2” and “Full Credit”
  - Few “Partial Credit 2”’s in practice
- Skill1 = Mathematical Language
- Skill2 = Convert Fractions and Compare Fractions
  - Fraction Manipulation
- Need two combination rules
  - No Credit -> Partial Credit. Only one skill relevant.
    - \* Can use any rule (“Compensatory” is default choice)
  - Partial Credit -> Full Credit.
    - \* Conjunctive model: both skills needed.
    - \* Less of Skill1 than of Skill2

## Inner Q-matrix

- Q-matrix inside node:
  - Rows are state transitions
  - Columns are skills (parent variables)

	Skill1	Skill2	Rule
Partial	1	0	Compensatory
Full	1	1	Conjunctive

- The function `PnodeQ(node)` allows setting the node level Q-matrix.

- PnodeQ(node) = TRUE implies all 1's in Q-matrix.

## Complex Example

- Now use function DPCGadget() to edit with full model.

```
CRItem <- Pnode(CRItem) ## Force into Pnode protocol.
PnodeLink(CRItem) <- "partialCredit"
PnodeRules(CRItem) <- list("Compensatory","OffsetDisjunctive")
PnodeAlphas(CRItem) <- list(c(Skill1=1),1)
PnodeBetas(CRItem) <- list(-1,c(Skill1=-1,Skill2=1))
PnodeQ(CRItem) <- matrix(as.logical(c(1,0,1,1)),2,2,byrow = TRUE)
PnodePriorWeight(CRItem) <- 10 ## Used for learning
calcDPCFrame(ParentStates(CRItem),PnodeStates(CRItem),
             PnodeLnAlphas(CRItem),PnodeBetas(CRItem),
             PnodeRules(CRItem),PnodeLink(CRItem),Q=PnodeQ(CRItem))
```

```
## Skill1 Skill2 FullCredit PartialCredit NoCredit
## 1 H H 0.9647686 0.03403099 0.00120040
## 2 M H 0.8223300 0.15022614 0.02744384
## 3 L H 0.3519553 0.33299278 0.31505193
## 4 H M 0.9647686 0.03403099 0.00120040
## 5 M M 0.8223300 0.15022614 0.02744384
## 6 L M 0.3519553 0.33299278 0.31505193
## 7 H L 0.9647686 0.03403099 0.00120040
## 8 M L 0.8223300 0.15022614 0.02744384
## 9 L L 0.3519553 0.33299278 0.31505193
```

```
BuildTable(CRItem)
CRItem <- DPCGadget(CRItem)
```

```
##
## Listening on http://127.0.0.1:4454
```

```
CRItem[]
```

```
## Skill1 Skill2 CRItem.FullCredit CRItem.PartialCredit CRItem.NoCredit
## 1 H H 0.9647686 0.03403099 0.00120040
## 2 M H 0.8223300 0.15022615 0.02744384
## 3 L H 0.3519553 0.33299279 0.31505191
## 4 H M 0.9647686 0.03403099 0.00120040
## 5 M M 0.8223300 0.15022615 0.02744384
## 6 L M 0.3519553 0.33299279 0.31505191
## 7 H L 0.9647686 0.03403099 0.00120040
## 8 M L 0.8223300 0.15022615 0.02744384
## 9 L L 0.3519553 0.33299279 0.31505191
```

```
PnodeQ(CRItem)
```

```
## Skill1 Skill2
## FullCredit TRUE FALSE
## PartialCredit TRUE TRUE
```

## Peanut Functions Summary

- `Pnode()` – converts a Netica node into a Peanut node
- `NodeLevels(node) <- effectiveThetas(PnodeNumStates(node))` – Sets up parent states.
- `PnodeLink(node)` – Link Function
- `PnodeRules(node)` – (list of) Combination Rules
- `PnodeLnAlphas(node)`, `PnodeAlphas(node)` – (list of) (vectors of) discriminations
- `PnodeBetas(node)` – (list of) (vectors of) difficulties
- `PnodeLinkScale(node)` – link scale parameter (for “normalLink”)
- `PnodeQ(node)` – Inner Q-matrix (TRUE = all 1’s)
- `PnodePriorWeight(node)` – prior strength for GEM algorithm learning
- `BuildTable(node)` – builds the table.

## Peanut Node Gadgets

- `CompensatoryGadget` – For simple Multiple-A models
- `OffsetGadget` – For simple Multiple-B models
- `RegressionGadget` – For normal link function models (no parent case)
- `DPCGadget` – For complex models
  - inner Q-matrix
  - different rules per row