

DiBello Models

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Parameterized Bayesian Networks

- In a discrete Bayesian Network, the *parameters* are the *conditional probability tables* (CPTs).
- Size of CPT grows exponentially with number of parents.
- In educational models, CPTs should be monotonic: higher skill states should imply higher probability of success.
- When learning CPTs from data, if skill variables are correlated certain combinations will be rare in data:
 - Skill 1 is high and Skill 2 is low
 - Skill 2 is low and Skill 1 is high
 - This makes for low effective sample size (high standard errors) when estimating CPTs from data.

Conditional Probability Tables

Lets Make a some Simple CPTs

Load PNetica (which loads Peanut and CPTtools), and start session. Build a blank Network.

```
library(PNetica)
```

```
## Loading required package: RNetica
```

```
## Loading required package: CPTtools
```

```
## Loading required package: Peanut
```

```
## Loading required package: futile.logger
```

```
sess <- NeticaSession()
```

```
startSession(sess)
```

```
## Netica 6.07 Linux (AFC164), (C) 1992-2019 Norsys Software Corp.
```

```
##
```

```
## Netica is operating without a password; there are some limitations.
```

```
tNet <- CreateNetwork("tNet",sess)
```

The following packages are loaded.

- CPTtools – Tools for building Conditional Probability Tables.
- RNetica – Interface to Netica
- Peanut – Object-oriented parameterized network protocol.
- PNetica – Peanut implementation for Netica

Create a Simple Network.

Create two parent nodes: Skill1 and Skill2, and a child node, CRItem.

```
Skills <- NewDiscreteNode(tNet,paste("Skill",1:2,sep=""),c("H","M","L"))
CRItem <- NewDiscreteNode(tNet,"CRItem",c("FullCredit","PartialCredit","NoCredit"))
NodeParents(CRItem) <- Skills
NodeParents(Skills[[2]]) <- Skills[1]
```

The Shape of CPTs

Skill1 has no parents, so unconditional CPT.

```
Skills[[1]] []
```

```
## Skill1.H Skill1.M Skill1.L
##      NA      NA      NA
```

Node that in RNetica the [] operator can be used to access the CPT of a node.

Skill2 has one parent, so conditional CPT.

```
Skills[[2]] []
```

```
## Skill1 Skill2.H Skill2.M Skill2.L
## 1      H      NA      NA      NA
## 2      M      NA      NA      NA
## 3      L      NA      NA      NA
```

CRItem has two parents, for total of nine (3x3) rows.

```
CRItem[]
```

```
## Skill1 Skill2 CRItem.FullCredit CRItem.PartialCredit CRItem.NoCredit
## 1      H      H                  NA                  NA                  NA
## 2      M      H                  NA                  NA                  NA
## 3      L      H                  NA                  NA                  NA
## 4      H      M                  NA                  NA                  NA
## 5      M      M                  NA                  NA                  NA
## 6      L      M                  NA                  NA                  NA
## 7      H      L                  NA                  NA                  NA
## 8      M      L                  NA                  NA                  NA
## 9      L      L                  NA                  NA                  NA
```

The [<- operator for NeticaNodes

RNetica maps the assignment operator for [] ([<-) to provide a wide variety of behaviors.

Both [and [<- allow the user to specify a specific row or cell, or group of rows and cells. This is similar, but not quite the same as the [operator behavior for matrixes and data frames.

Single Row:

```
CRItem[Skill1="H",Skill2="H"] <- c(.7,.2,.1)
CRItem["H","H"]
```

```
## Skill1 Skill2 CRItem.FullCredit CRItem.PartialCredit CRItem.NoCredit
## 1      H      H                  0.7                  0.2                  0.1
```

Conditional Tables

Multiple Rows:

```
CRItem[Skill2="M"] <- c(.25,.5,.25)
CRItem["M",c("H","M")] <-c(.25,.5,.25)
CRItem[, "M"]
```

```
## Skill1 Skill2 CRItem.FullCredit CRItem.PartialCredit CRItem.NoCredit
## 1 H M 0.25 0.5 0.25
## 2 M M 0.25 0.5 0.25
## 3 L M 0.25 0.5 0.25
```

```
CRItem["M",]
```

```
## Skill1 Skill2 CRItem.FullCredit CRItem.PartialCredit CRItem.NoCredit
## 1 M H 2.500000e-01 5.000000e-01 2.500000e-01
## 2 M M 2.500000e-01 5.000000e-01 2.500000e-01
## 3 M L -3.396031e+38 -3.396031e+38 -3.396031e+38
```

Fill out a conjunctive model.

```
CRItem["L",] <- c(.1,.2,.7)
CRItem[, "L"] <- c(.1,.2,.7)
CRItem[]
```

```
## Skill1 Skill2 CRItem.FullCredit CRItem.PartialCredit CRItem.NoCredit
## 1 H H 0.70 0.2 0.10
## 2 M H 0.25 0.5 0.25
## 3 L H 0.10 0.2 0.70
## 4 H M 0.25 0.5 0.25
## 5 M M 0.25 0.5 0.25
## 6 L M 0.10 0.2 0.70
## 7 H L 0.10 0.2 0.70
## 8 M L 0.10 0.2 0.70
## 9 L L 0.10 0.2 0.70
```

Conditional Probability Frames and Conditional Probability Arrays

When there are two or more parent variables, there are two possible views of the CPT: * *Conditional Probability Frame* (CPF) which is a data frame where rows represent configurations of parent variables. + First p rows represent parent configuration + Last $|States|$ rows represent child states. + Numeric part is the conditional probability table - Note: `calcXXXFrame()` and `calcXXXTable()` methods in CPTtools + CPFs can be used on the RHS of `[<-` operator for NeticaNodes, to set the CPT.

Array view

- *Conditional Probability Array* (CPA) which is $p + 1$ dimensional array.

The functions `as.CPF` and `as.CPA` convert back and forth between the two views:

```
as.CPA(CRItem[])
```

```
## , , CRItem = FullCredit
##
## Skill2
## Skill1 H M L
## H 0.70 0.25 0.1
## M 0.25 0.25 0.1
```

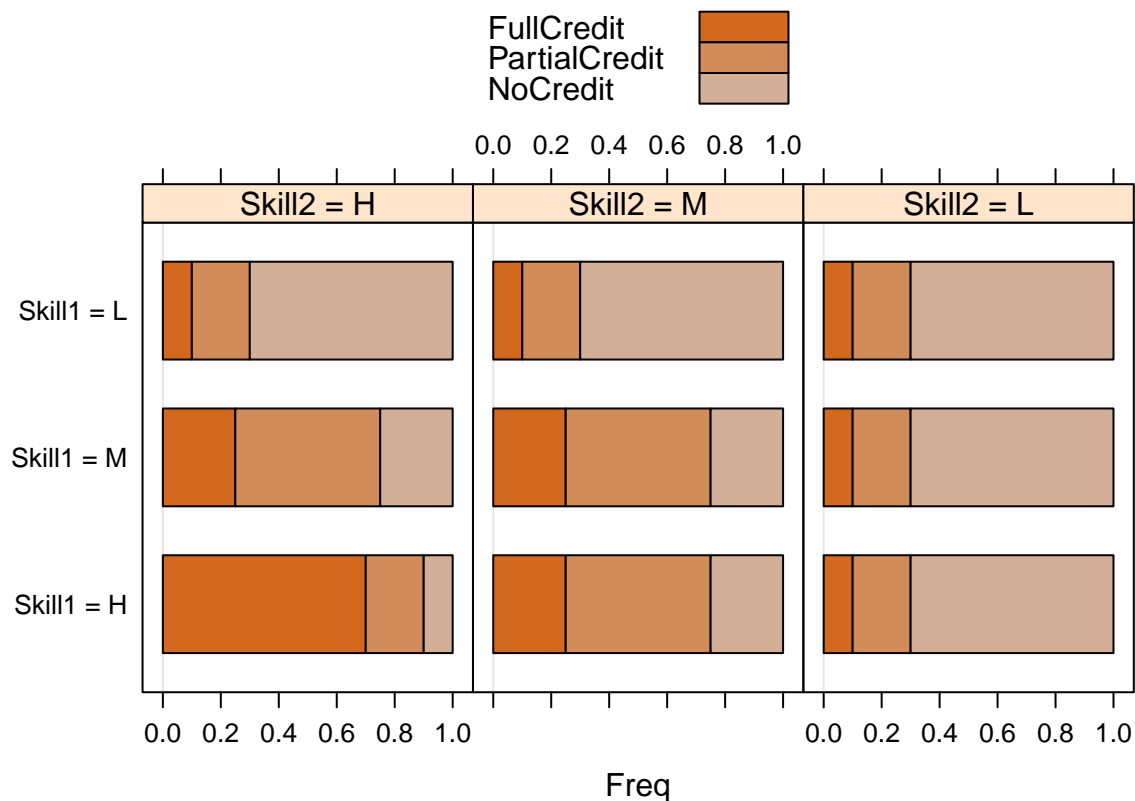
```
##      L 0.10 0.10 0.1
##
## , , CRItem = PartialCredit
##
##      Skill2
## Skill1  H   M   L
##      H 0.2 0.5 0.2
##      M 0.5 0.5 0.2
##      L 0.2 0.2 0.2
##
## , , CRItem = NoCredit
##
##      Skill2
## Skill1  H   M   L
##      H 0.10 0.25 0.7
##      M 0.25 0.25 0.7
##      L 0.70 0.70 0.7
##
## attr("class")
## [1] "CPA" "array"
```

Graphing a conditional probability table.

The function `barchart.CPF` (which extends the lattice function `barchart`) will build a visualization of the CPF.

The `baseCol` argument can be any R color specification, it is then used as the base color for the graph.

```
barchart.CPF(CRItem[],baseCol="chocolate")
```



How far have we come?

- The `[]` function for `NeticaNodes` is a very convenient way for accessing and manipulating CPTs
- It uses a data-frame representation, the *CPF*
- If we can make a CPF, we can set the table for a node.
- The package `CPTtools` is all about making CPFs!

The DiBello Models

A Short History

- When building CPT for Biomass, Lou DiBello had an idea.
- Map each row of the CPT onto an *effective Theta*
- Then use IRT model (Samejima's Graded Response) to calculate CPTs for each row.
- For multivariate parents, use a *structure function* or *combination rule* to combine individual effective thetas for each parent into a single effective theta.
 - *Compensatory*: (weighted) average of parents
 - *Conjunctive*: minimum of parents
 - *Disjunctive*: maximum of parents

The DiBello procedure: Effective Thetas

1 Map the states of the parent variables onto the standard normal (theta) scale.

```
effectiveThetas(2)
```

```
## [1]  0.6744898 -0.6744898
```

```
effectiveThetas(3)
```

```
## [1]  0.9674216  0.0000000 -0.9674216
```

```
effectiveThetas(4)
```

```
## [1]  1.1503494  0.3186394 -0.3186394 -1.1503494
```

The function `PnodeStateValues()` sets the effective Thetas for a node.

The function `ParentNodeTVals()` fetches the effective Thetas for the

DiBello Procedure: Combination Rules

2 Combine the parent variables using a *combination rule* to create a single effective theta for each row.

+ The combination rule generally has slope (discrimination) parameters (α 's or a 's)

+ The combination rule generally has difficulty (intercept) parameters (β 's or b 's)

+ Some rules (e.g., ``Compensatory``) have multiple- a 's, some (e.g., ``OffsetConjunctive``) have multiple- b 's

+ Some link functions allow (or even require) different b 's for each state of the child variable (step difficulties).

+ The partial credit link function allows different a 's as well.

DiBello Procedure 3:

3 Convert the effective thetas to conditional probabilities using a *link function* (IRT-like models)

```
+ `gradedResponse` -- Lou's original suggestion
+ `partialCredit` -- More flexible alternative
+ `normalLink` -- Regression-like model for proficiency variables.
  - Requires a _link scale parameters_
```

The function `calcDPCFrame` in the `CPTtools` package does the work. (DPC = Discrete Partial Credit)

Mapping Parent States onto the Theta Scale

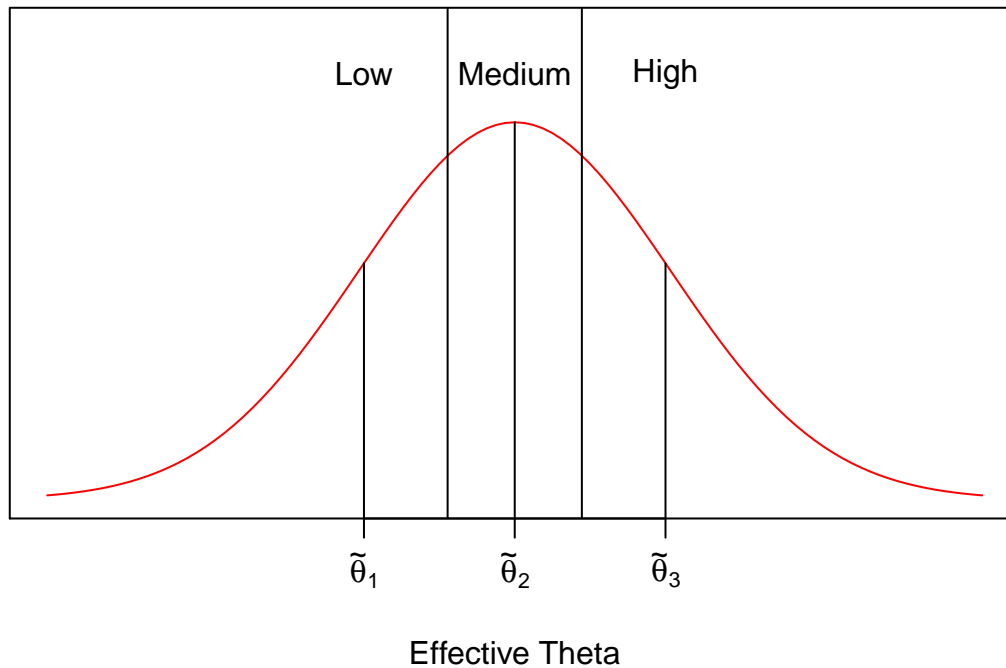
- Effective theta scale is a logit scale corresponds to mean 0 SD 1 in a “standard” population.
- Want the effective theta values to be equally spaced on this scale
- Want the marginal distribution implied by the effective thetas to be uniform (unit of the combination operator)

*What the effective theta transformation to be effectively invertible (this is reason to add the 1.7 to the IRT equation).

Equally spaced points in Normal Measure

- Assume variable has M states: $0, \dots, M - 1$
- Region m will have lower bound m/M quantile and upper bound at $(m + 1)/M$ quantile.
- Midpoint will be at $(m + \frac{1}{2})/M$ quantile

```
states <- c("Low", "Medium", "High")
M <- length(states)
c <- qnorm((1L:(M-1L))/M, 0, 1)
theta <- qnorm((1L:M - .5)/M, 0, 1)
curve(dnorm(x), xlim=c(-3, 3), xaxt="n", yaxt="n", ylim=c(0, .5), col="red",
      ylab="", xlab="Effective Theta")
segments(c, -.1, c, .6)
segments(theta, -.1, theta, dnorm(theta))
text(theta, .45, states)
axis(1, theta, do.call(expression,
                        lapply(1:M, function (m)
                              substitute(tilde(theta)[m], list(m=m))))))
```



Setting up effective Thetas

The function `effectiveThetas` calculates this.

```
effectiveThetas
```

```
## function (nlevels)
## {
##   rev(qnorm((2 * (1:nlevels) - 1)/(2 * nlevels), 0, 1))
## }
## <bytecode: 0x558531323a88>
## <environment: namespace:CPTtools>
```

```
effectiveThetas(3)
```

```
## [1]  0.9674216  0.0000000 -0.9674216
```

```
## We will need this for building CPTs later.
```

```
PnodeStateValues(Skills[[1]]) <- effectiveThetas(PnodeNumStates(Skills[[1]]))
PnodeStateValues(Skills[[2]]) <- effectiveThetas(PnodeNumStates(Skills[[2]]))
```

Combination Rules

- **Compensatory** – more of one skill compensates for lack of another
- **Conjunctive** – weakest skill dominates relationship
- **Disjunctive** – strongest skill dominates relationship
- **Inhibitor** – minimum threshold of Skill 1 needed, then Skill 2 takes over (special case of conjunctive)
- **Multi-b rules:**
 - **OffsetConjunctive** – like conjunctive model, but with separate b 's for each parent instead of separate a 's
 - **Offset Disjunctive** – like disjunctive rule, but with separate b 's for each parent instead of separate a 's.

Compensatory Rule

- Weighted average of inputs
- One α (slope) for each parent variable (k) and state (s): $\alpha_{k,s}$
- One β (difficulty) for each state of the child variable (except the last): β_s

$$\tilde{\theta} = \frac{1}{\sqrt{K}} \sum_k \alpha_{k,s} \tilde{\theta}_{k,m_k} - \beta_s$$

* Factor $1/\sqrt{K}$ is a variance stabilization term. (Make variance independent of number of parents.)

Conjunctive and Disjunctive Rules (Multi-a)

- Replace sum (and square root of K) with **min** or **max**
- Conjunctive: All skills needed; weakest skill dominates

$$\tilde{\theta} = \min_k \alpha_{k,s} \tilde{\theta}_{k,m_k} - \beta_s$$

- Disjunctive: Any skills needed; strongest skill dominates

$$\tilde{\theta} = \max_k \alpha_{k,s} \tilde{\theta}_{k,m_k} - \beta_s$$

- Not sure what the different slopes mean in this context

Conjunctive and Disjunctive Rules (Multi-b)

- Different skills may have different demands in a task
 - Skill 1 must be high, but Skill 2 only medium
- Model this with different difficulties (b 's) for each parent skill.
- OffsetConjunctive: All skills needed; weakest skill dominates

$$\tilde{\theta} = \alpha_s \min_k (\tilde{\theta}_{k,m_k} - \beta_{k,s})$$

- Disjunctive: Any skills needed; strongest skill dominates

$$\tilde{\theta} = \alpha_s \max_k (\tilde{\theta}_{k,m_k} - \beta_{k,s})$$

Implementation in CPTtools

- Compensatory, Conjunctive, Disjunctive, OffsetConjunctive and OffsetDisjunctive are implemented as functions in CPTtools
 - This set is expandable by adding new functions with the same signature
- The function `eThetaFrame` demonstrates how this works.
- Note: Uses $\log(\alpha)$ rather than α as slope parameter.

```
eThetaFrame(ParentStates(CRItem), log(c(Skill1=1.2, Skill2=.8)), 0,
             Compensatory)
```

##	Skill1	Skill2	Skill1.theta	Skill2.theta	Effective.theta
## 1	H	H	0.9674216	0.9674216	1.3681407
## 2	M	H	0.0000000	0.9674216	0.5472563
## 3	L	H	-0.9674216	0.9674216	-0.2736281
## 4	H	M	0.9674216	0.0000000	0.8208844

## 5	M	M	0.0000000	0.0000000	0.0000000
## 6	L	M	-0.9674216	0.0000000	-0.8208844
## 7	H	L	0.9674216	-0.9674216	0.2736281
## 8	M	L	0.0000000	-0.9674216	-0.5472563
## 9	L	L	-0.9674216	-0.9674216	-1.3681407

Try changing the slopes and intercepts

Offset Style Rules:

Almost the same, except now we expect beta to be a vector instead of alpha.

```
eThetaFrame(ParentStates(CRItem),log(1),c(Skill1=.5,Skill2=-.5),
            OffsetConjunctive)
```

##	Skill1	Skill2	Skill1.theta	Skill2.theta	Effective.theta
## 1	H	H	0.9674216	0.9674216	0.4674216
## 2	M	H	0.0000000	0.9674216	-0.5000000
## 3	L	H	-0.9674216	0.9674216	-1.4674216
## 4	H	M	0.9674216	0.0000000	0.4674216
## 5	M	M	0.0000000	0.0000000	-0.5000000
## 6	L	M	-0.9674216	0.0000000	-1.4674216
## 7	H	L	0.9674216	-0.9674216	-0.4674216
## 8	M	L	0.0000000	-0.9674216	-0.5000000
## 9	L	L	-0.9674216	-0.9674216	-1.4674216

Try changing the slopes and intercepts, and changing the rule for OffSetDisjunctive

Link Functions

- Graded Response Model
- Normal (Regression) Model
- Partial Credit Model
- 2PL (Special case of graded response or partial credit)

Graded Response model

- Models $\Pr(X \geq s)$
- Probabilities are differences between curves
- To keep the curves from crossing, discrimination parameters must be the same for all s

```
PnodeLink(node) <- "gradedResponse"
```

Normal (Regression) model

- Effective theta is mean predictor
- Add a residual variance (link scale parameter)
- Calculate probabilities that value falls into certain regions

```
PnodeLink(node) <- "normalLink"
PnodeLinkScale(node) <- 1
```

Generalized partial credit model

- Models state transitions: $\Pr(X \geq s | X \geq s - 1)$
- Does not need the discrimination parameters to be the same
- Does not even need the combination rules to be the same

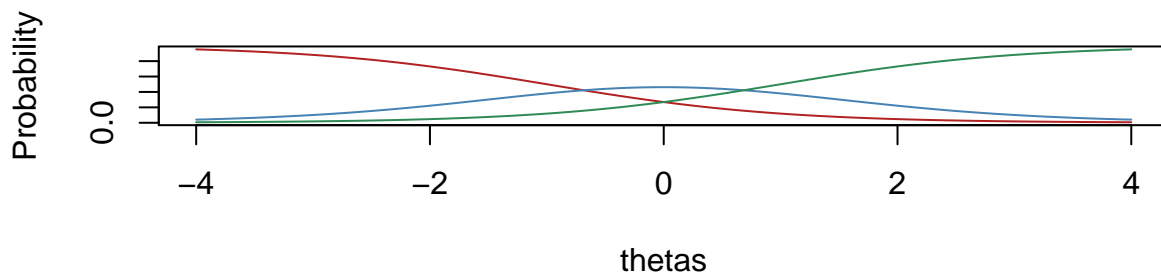
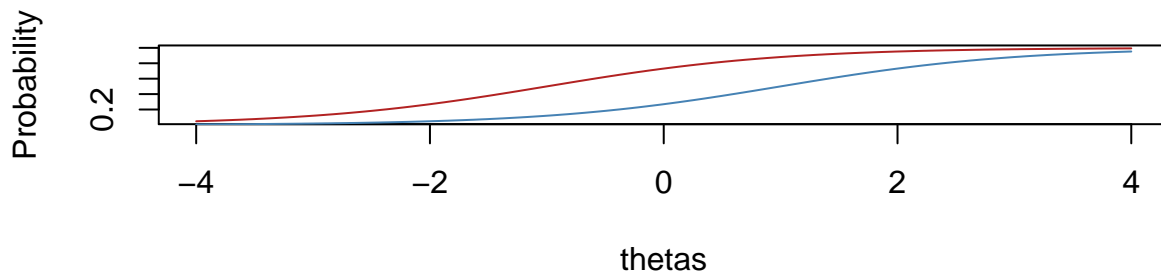
```
PnodeLink(node) <- "partialCredit"
node <- Pnode(node) ## Partial credit is the default.
```

Graded Response (DiBello–Samejima models)

Samejima's (1969) psychometric model for graded responses

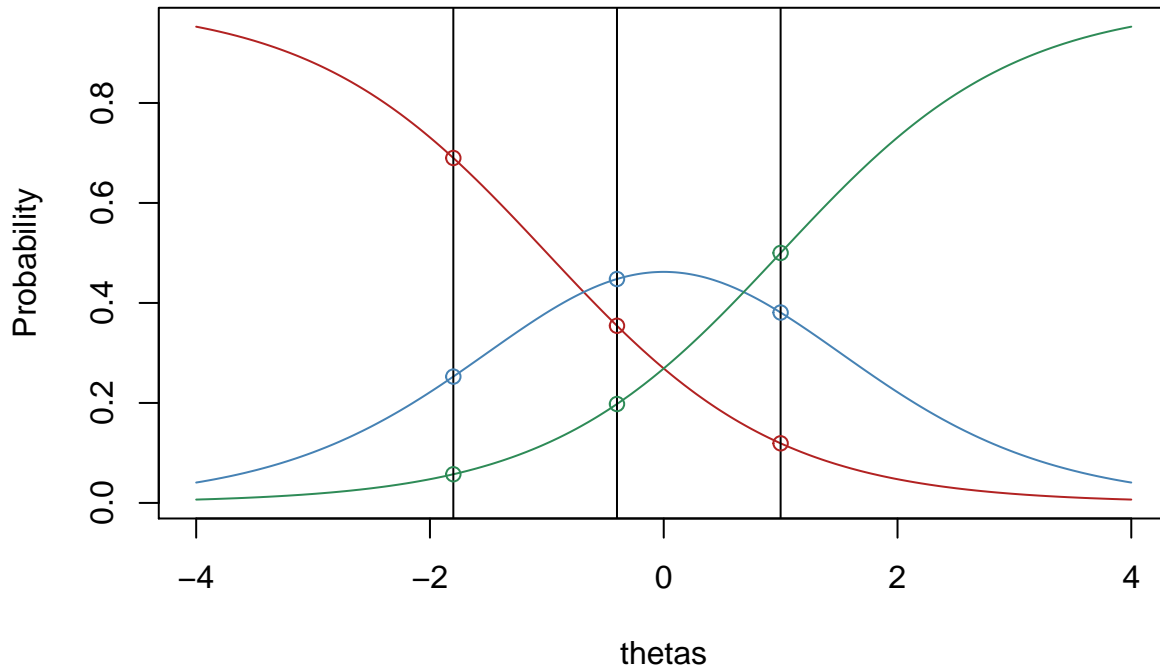
$$\Pr(X_{i,j} \geq k | \theta_i) = \text{logit}^{-1}(1.7(a_j\theta_i - b_{j,k}))$$

$$\Pr(X_{i,j} = k | \theta_i) = \Pr(X_{i,j} \geq k | \theta_i) - \Pr(X_{i,j} \geq k + 1 | \theta_i)$$



Continuous -> Discrete

Evaluate Samejima's graded response model at the effective theta values.



```
##      Theta State2 State1 State0
## Low  -1.8  0.057  0.253  0.690
## Med  -0.4  0.198  0.448  0.354
## High   1.0  0.500  0.381  0.119
```

Representing Graded Response Models in Peanut

- Peanut is a framework that allows us to attach the parameters to nodes in the graph.
 - PNetica implements this for NeticaNode objects
- PnodeLink(node) accesses the link function
 - Should have value “gradedResponse” for graded response models.
- PnodeRules(node) accesses the rules.
 - For now, stick to multiple-a types: Compensatory, Conjunctive and Disjunctive.

Setting the parameters

- PnodeLnAlphas(node) or PnodeAlphas(node) gives the slope parameters.
 - This should be a vector which components corresponding to the parents.
 - In general, vectors are used to represent multiple parents.
- PnodeBetas(node) gives the difficulty parameters.
 - This should be a *list* with one fewer elements than there are states (the last state is used for normalization).
 - In general, lists are used to represent multiple states.

Building the Table

- BuildTable(node) builds the table.
 - NodeLevels of parents need to be set.
 - NodePriorWeight (used in learning algorithm) needs to be set.

```
CRItem <- Pnode(CRItem) ## Force into Pnode protocol.
PnodeLink(CRItem) <- "gradedResponse"
PnodeRules(CRItem) <- "Compensatory"
```

```

PnodeAlphas(CRItem) <- c(1.2,.8)
PnodeBetas(CRItem) <- list(.25, -.25)
PnodePriorWeight(CRItem) <- 10 ## Used for learning
calcDPCFrame(ParentStates(CRItem),PnodeStates(CRItem),
              PnodeLnAlphas(CRItem),PnodeBetas(CRItem),
              PnodeRules(CRItem),PnodeLink(CRItem))

```

```

## Skill1 Skill2 FullCredit PartialCredit NoCredit
## 1      H      H 0.86998648    0.06997425 0.06003927
## 2      M      H 0.62371241    0.17128816 0.20499942
## 3      L      H 0.29107519    0.19888420 0.51004061
## 4      H      M 0.72521985    0.13540669 0.13937347
## 5      M      M 0.39532092    0.20935817 0.39532092
## 6      L      M 0.13937347    0.13540669 0.72521985
## 7      H      L 0.51004061    0.19888420 0.29107519
## 8      M      L 0.20499942    0.17128816 0.62371241
## 9      L      L 0.06003927    0.06997425 0.86998648

```

```
BuildTable(CRItem)
```

```

CRItem <- CompensatoryGadget(CRItem)
CRItem[]

```

Don't Cross the curves!

Egon Spengler: There's something very important I forgot to tell you. **Peter Venkman:** What? **Egon:** Don't cross the streams. **Venkman:** Why? **Egon:** It would be bad. **Venkman:** I'm fuzzy on the whole good/bad thing. What do you mean, "bad"? **Egon:** Try to imagine all life as you know it stopping instantaneously, and every molecule in your body exploding at the speed of light. **Ray Stantz:** [shocked gasp] Total protonic reversal. **Venkman:** Right. That's bad. Okay. All right. Important safety tip. Thanks, Egon. *Ghostbusters*

Actually, not as bad as crossing the proton beams, can produce negative probabilities.

CPTtools corrects, but still puts restrictions on parameters.

In particular, must have a common discrimination for all states of the child variable to ensure curves don't cross.

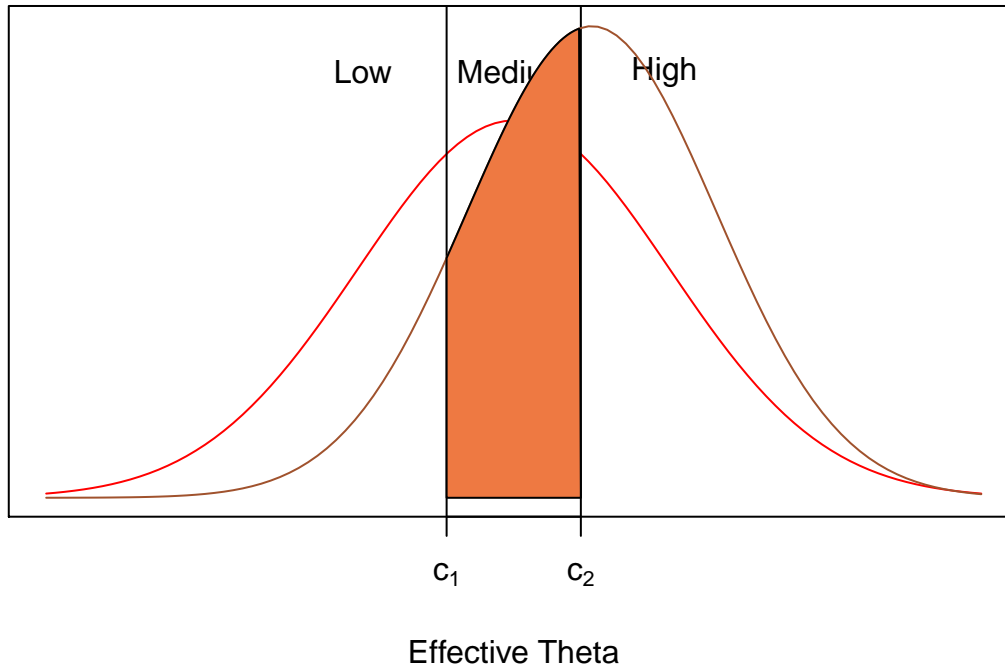
Downslide of Graded Response Model

- Need to keep curves from crossing restricts discrimination parameter
 - In *Physics Playground* (v. 1) for some levels difference between **Silver** trophy and **Gold** trophy had more evidence (higher discrimination) than difference between **Silver** and **none**
 - All steps must have the same parent variables and the same combination rule.
- Models probability of achieving certain level of performance, not step between levels.
- Generalized Partial Credit (GPC) model does not have these downsides.
- Note Graded Response and GPC are the same when child variable has only two states.

Normal (Regression) Model

- As with effective theta transformation, start by dividing theta region up into equally spaced intervals
- Calculate offset curve:
 - mean is effective theta

- SD, s , is *link scale parameter* *Conditional probabilities:
- area under curve between cut points



```
##           Low      Medium      High
## 0.1223318 0.3431666 0.5345016
```

Normal Link (Regression Model) features

- Link function is inverse of the mapping from states to effective thetas
 - Rounding error, but no scale distortion
 - Good for proficiency variables
- Can be used for no parent case.
- Often better to use intercept (negative difficulty) rather than difficulty.
- Can use R^2 instead of the link scale parameter, σ

$$R^2 = \frac{1/K \sum_k \alpha_{k,s}^2}{1/K \sum_k \alpha_{k,s}^2 + \sigma^2}$$

- Note: Latent (tetrachoric) correlations, not observed score correlations
- Can use factor analysis output to get model structure and parameters (Almond, 2010)

Normal Link: No Parent case

- `PnodeLink(node)` is now “normalLink”
- Now need `PnodeLinkScale(node)`, residual standard deviation (σ)
- Rule doesn’t matter, use `PnodeRules(node) = "Compensatory"`
- Should be only one `PnodeBeta(node)`

```
Skill11 <- Pnode(Skills[[1]]) ## Force into Pnode protocol.
PnodeLink(Skill11) <- "normalLink"
PnodeLinkScale(Skill11) <- .8
PnodeRules(Skill11) <- "Compensatory"
PnodeAlphas(Skill11) <- numeric()
```

```

PnodeBetas(Skill11) <- list(.25)
PnodePriorWeight(Skill11) <- 10 ## Used for learning
calcDPCFrame(ParentStates(Skill11),PnodeStates(Skill11),
              PnodeLnAlphas(Skill11),PnodeBetas(Skill11),
              PnodeRules(Skill11),PnodeLink(Skill11),
              PnodeLinkScale(Skill11))

##           H           M           L
## 1 0.1974099 0.391954 0.4106361

BuildTable(Skill11)

## WARN [2021-06-04 10:34:07] Alpha vector for node Skill11 is empty.
Skill11 <- RegressionGadget(Skill11)
Skill11[]

```

Normal Link: One Parent case

- PnodeLink(node) is now “normalLink”
- Now need PnodeLinkScale(node), residual standard deviation (σ)
- Works best with PnodeRules(node) = “Compensatory”
- Should be only one PnodeBeta(node)

```

Skill12 <- Pnode(Skills[[2]]) ## Force into Pnode protocol.
PnodeLink(Skill12) <- "normalLink"
PnodeLinkScale(Skill12) <- .6
PnodeRules(Skill12) <- "Compensatory"
PnodeAlphas(Skill12) <- c(.8)
PnodeBetas(Skill12) <- list(-.25)
PnodePriorWeight(Skill12) <- 10 ## Used for learning
calcDPCFrame(ParentStates(Skill12),PnodeStates(Skill12),
              PnodeLnAlphas(Skill12),PnodeBetas(Skill12),
              PnodeRules(Skill12),PnodeLink(Skill12),
              PnodeLinkScale(Skill12))

## Skill11           H           M           L
## 1      H 0.83859093 0.1537431 0.007665989
## 2      M 0.38162636 0.4900907 0.128282900
## 3      L 0.05579268 0.3824800 0.561727270

BuildTable(Skill12)
Skill12 <- RegressionGadget(Skill12)

## Loading required package: shiny
##
## Listening on http://127.0.0.1:7192

Skill12[]

## Skill11 Skill12.H Skill12.M Skill12.L
## 1      H 0.83859092 0.1537431 0.007665989
## 2      M 0.38162637 0.4900908 0.128282905
## 3      L 0.05579268 0.3824801 0.561727285

```

Partial Credit Models

- Observable variable takes on states $0, \dots, S$
- Model transition probabilities:

$$P_{s|s-1}(\tilde{\theta}) = \Pr(X \geq s | X \geq s-1, \tilde{\theta}) = \text{logit}^{-1} 1.7 Z_s(\tilde{\theta})$$

- Define $Z_0() = 0$.
- $Z_s()$ can vary with s :
 - Different parameters
 - Different functional forms
 - Can easily switch between multi-a and multi-b combination rules
 - Can use only a subset of the parents!
- Need to define combination rule and parameters for each state (except state 0).
- `PnodeLnAlphas`, `PnodeBetas` and `PnodeRules` are now lists (one element per state)

Partial Credit Link:

- Probability of X being in state s is:

$$\Pr(X = s | \tilde{\theta}) = \frac{\prod_{r=0}^s P_{r|r-1}(\tilde{\theta})}{C},$$

where C is a normalization constant.

- Can convert the products to sums

$$\Pr(X = s | \tilde{\theta}) = \frac{\exp\left(1.7 \sum_{r=0}^s Z_r(\tilde{\theta})\right)}{\sum_{R=0}^S \exp\left(1.7 \sum_{r=0}^R Z_r(\tilde{\theta})\right)}$$

Simple Case 1: Multiple-A rules

- These look a lot like graded response
- `PnodeLink(pnode) = "partialCredit"`
- `PnodeRules(pnode)` is a single value
 - “Compensatory”, “Conjunctive”, “Disjunctive”
- `PnodeLnAlphas(pnode)` is a *vector* corresponding to parents
- `PnodeBetas(pnode)` is a *list* corresponding to states.
 - $Z_s()$ has the same functional form and the same parameters except for b 's
- Use `CompensatoryGadget` to edit this style table.

Simple Case: Example

```
CRItem <- Pnode(CRItem) ## Force into Pnode protocol.
PnodeLink(CRItem) <- "partialCredit"
PnodeRules(CRItem) <- "Compensatory"
PnodeAlphas(CRItem) <- c(1.2, .8)
PnodeBetas(CRItem) <- list(.25, -.25)
PnodePriorWeight(CRItem) <- 10 ## Used for learning
calcDPCFrame(ParentStates(CRItem), PnodeStates(CRItem),
             PnodeLnAlphas(CRItem), PnodeBetas(CRItem),
             PnodeRules(CRItem), PnodeLink(CRItem))
```

```
## Skill1 Skill2 FullCredit PartialCredit NoCredit
## 1 H H 0.862821165 0.1289427 0.008236118
## 2 M H 0.568546469 0.3430058 0.088447725
## 3 L H 0.167478982 0.4079015 0.424619527
## 4 H M 0.694323128 0.2630736 0.042603245
## 5 M M 0.283318992 0.4333620 0.283318992
## 6 L M 0.042603245 0.2630736 0.694323128
## 7 H L 0.424619527 0.4079015 0.167478982
## 8 M L 0.088447725 0.3430058 0.568546469
## 9 L L 0.008236118 0.1289427 0.862821165
```

```
BuildTable(CRItem)
```

```
CRItem <- CompensatoryGadget(CRItem)
CRItem[]
```

Simple Case 2: Multiple-B rules

- These look a lot like multiple-a rules.
- `PnodeLink(pnode)` = "partialCredit"
- `PnodeRules(pnode)` is a single value
 - "OffsetConjunctive", "OffsetDisjunctive"
- `PnodeLnAlphas(pnode)` is a *list* corresponding to states
- `PnodeBetas(pnode)` is a *vector* corresponding to parent.
 - $Z_s()$ has the same functional form and the same parameters except for b 's
- Use `OffsetGadget` to edit this style table.

Case 2 example

```
CRItem <- Pnode(CRItem) ## Force into Pnode protocol.
PnodeLink(CRItem) <- "partialCredit"
PnodeRules(CRItem) <- "OffsetDisjunctive"
PnodeAlphas(CRItem) <- list(1.2,.8)
PnodeBetas(CRItem) <- c(.25, -.25)
PnodePriorWeight(CRItem) <- 10 ## Used for learning
calcDPCFrame(ParentStates(CRItem),PnodeStates(CRItem),
  PnodeLnAlphas(CRItem),PnodeBetas(CRItem),
  PnodeRules(CRItem),PnodeLink(CRItem))
```

```
## Skill1 Skill2 FullCredit PartialCredit NoCredit
## 1 H H 0.90960164 0.0759038 0.01449456
## 2 M H 0.90960164 0.0759038 0.01449456
## 3 L H 0.90960164 0.0759038 0.01449456
## 4 H M 0.75835519 0.1754952 0.06614958
## 5 M M 0.49311841 0.2961154 0.21076617
## 6 L M 0.49311841 0.2961154 0.21076617
## 7 H L 0.75835519 0.1754952 0.06614958
## 8 M L 0.19980267 0.3327296 0.46746769
## 9 L L 0.05957531 0.2574386 0.68298611
```

```
BuildTable(CRItem)
```

```
CRItem <- OffsetGadget(CRItem)
CRItem[]
```


Discrete Partial Credit model unleashed

- `PnodeRules(pnode)` is now a *list*
 - different rule for each state
- `PnodeLnAlphas(node)` is also a *list*
 - elements correspond to states
 - will be a vector or scalar according to corresponding rule.
- `PnodeBetas(node)` is also a *list*
 - elements correspond to states
 - will be a vector or scalar according to corresponding rule.
- A *list* corresponds to states of child variable (except last)
 - If a vector or scalar shows up where a list is expected, the same value is used for all states.
- A *vector* (within a list) corresponds to parents
- Could eliminate some parents (0 alpha, or infinite beta)
 - Or use *inner* (node specific) *Q*-matrix

Example: Math Word Problem

- Based on unpublished analysis by Cocke and Guo (personal communication 2011-07-11)
- Next Generation Sunshine State Standards Benchmark, MA.6.A.5.1, “Use equivalent forms of fractions, decimals, and percents to solve problems” (NGSSS, 2013)
- Sample problem: > John scored 75% on a test and Mary has 8 out of 12 correct on the same test. Each test item is worth the same amount of points. Who has the better score?

Scoring Rubric

State	Description	Skills
No Credit or off track	Null response	N/A
Partial Credit 1	Recognizes 75% and 8/12 as key elements	Mathematical Language
Partial Credit 2	Converts two fractions to a common form	Convert Fractions
Full Credit	Makes the correct comparison	Compare Fractions & Math Lang.

Model Refinement

- Collapse “Partial Credit 2” and “Full Credit”
 - Few “Partial Credit 2”’s in practice
- Skill1 = Mathematical Language
- Skill2 = Convert Fractions and Compare Fractions
 - Fraction Manipulation
- Need two combination rules

- No Credit -> Partial Credit. Only one skill relevant.
 - * Can use any rule (“Compensatory” is default choice)
- Partial Credit -> Full Credit.
 - * Conjunctive model: both skills needed.
 - * Less of Skill1 than of Skill2

Inner Q-matrix

- Q-matrix inside node:
 - Rows are state transitions
 - Columns are skills (parent variables)

Skill1	Skill2	Rule	
Partial	1	0	Compensatory
Full	1	1	Conjunctive

- The function `PnodeQ(node)` allows setting the node level Q-matrix.
- `PnodeQ(node) = TRUE` implies all 1’s in Q-matrix.

Complex Example

- Now use function `DPCGadget()` to edit with full model.

```
CRItem <- Pnode(CRItem) ## Force into Pnode protocol.
PnodeLink(CRItem) <- "partialCredit"
PnodeRules(CRItem) <- list("Compensatory", "OffsetDisjunctive")
PnodeAlphas(CRItem) <- list(c(Skill1=1), 1)
PnodeBetas(CRItem) <- list(-1, c(Skill1=-1, Skill2=1))
PnodeQ(CRItem) <- matrix(as.logical(c(1,0,1,1)), 2, 2, byrow = TRUE)
PnodePriorWeight(CRItem) <- 10 ## Used for learning
calcDPCFrame(ParentStates(CRItem), PnodeStates(CRItem),
              PnodeLnAlphas(CRItem), PnodeBetas(CRItem),
              PnodeRules(CRItem), PnodeLink(CRItem), Q=PnodeQ(CRItem))
```

```
## Skill1 Skill2 FullCredit PartialCredit NoCredit
## 1 H H 0.9647686 0.03403099 0.00120040
## 2 M H 0.8223300 0.15022614 0.02744384
## 3 L H 0.3519553 0.33299278 0.31505193
## 4 H M 0.9647686 0.03403099 0.00120040
## 5 M M 0.8223300 0.15022614 0.02744384
## 6 L M 0.3519553 0.33299278 0.31505193
## 7 H L 0.9647686 0.03403099 0.00120040
## 8 M L 0.8223300 0.15022614 0.02744384
## 9 L L 0.3519553 0.33299278 0.31505193
```

```
BuildTable(CRItem)
```

```
CRItem <- DPCGadget(CRItem)
CRItem[]
PnodeQ(CRItem)
```

Peanut Functions Summary

- `Pnode()` – converts a Netica node into a Peanut node
- `PnodeStateValues(node) <- effectiveThetas(PnodeNumStates(node))` – Sets up parent states.
- `PnodeLink(node)` – Link Function
- `PnodeRules(node)` – (list of) Combination Rules
- `PnodeLnAlphas(node)`, `PnodeAlphas(node)` – (list of) (vectors of) discriminations
- `PnodeBetas(node)` – (list of) (vectors of) difficulties
- `PnodeLinkScale(node)` – link scale parameter (for “normalLink”)
- `PnodeQ(node)` – Inner Q-matrix (TRUE = all 1’s)
- `PnodePriorWeight(node)` – prior strength for GEM algorithm learning
- `BuildTable(node)` – builds the table.

Peanut Node Gadgets

- `CompensatoryGadget` – For simple Multiple-A models
- `OffsetGadget` – For simple Multiple-B models
- `RegressionGadget` – For normal link function models (no parent case)
- `DPCGadget` – For complex models
 - inner Q-matrix
 - different rules per row